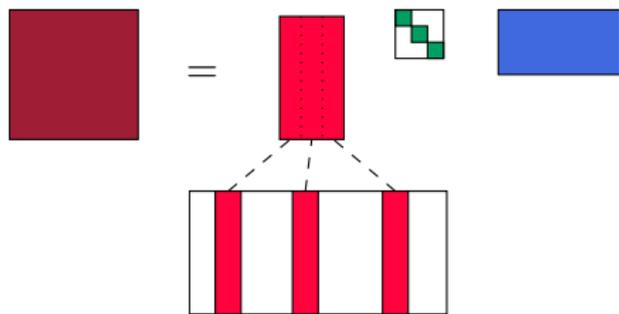


# A New Approach to Dictionary-Based Nonnegative Matrix Factorization

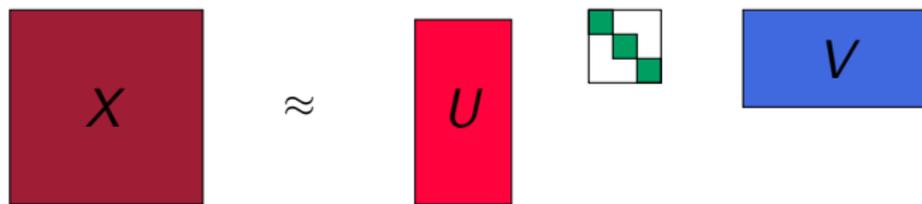


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# Nonnegative Matrix Factorization



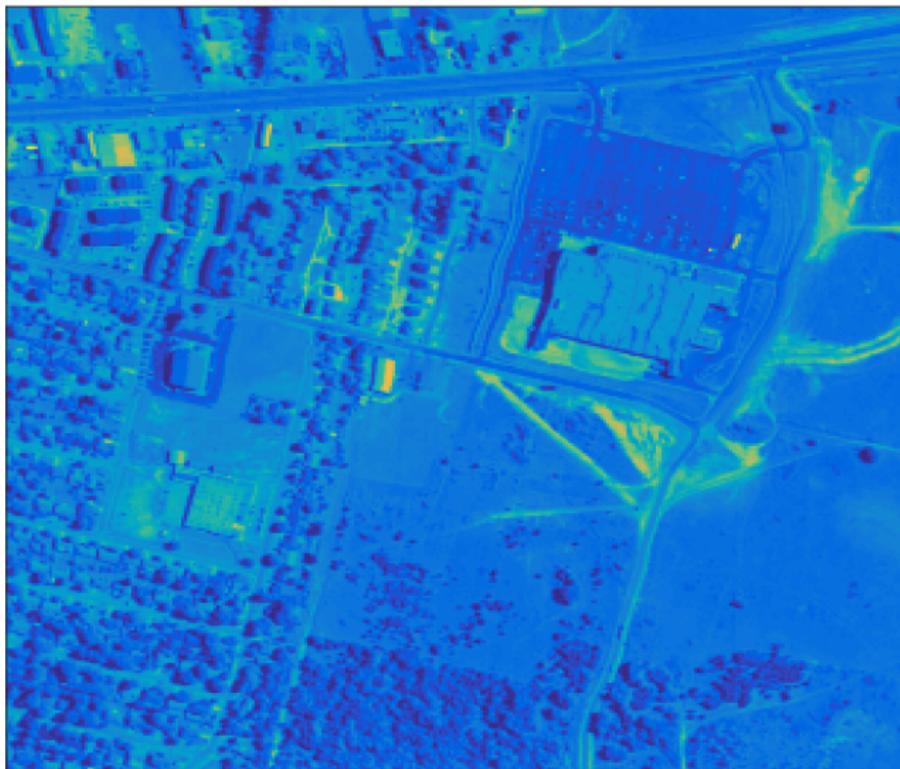
$$X \approx UV \iff X(:,j) \approx \sum_{k=1}^k U(:,k)V(k,j) \forall j.$$

where  $U \geq 0$  and  $V \geq 0$  element-wise.

## Uniqueness

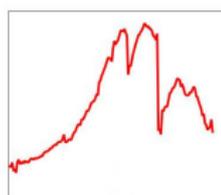
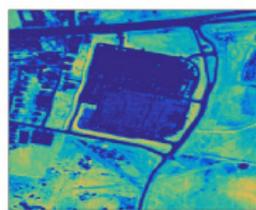
The NMF of a nonnegative matrix  $X$  is **not unique** unless some harsh sparsity conditions on  $X$  are met [Donoho 2004, Laurberg 2008, Huang 2013].

# Application to spectral unmixing of HSIs



# Application to spectral unmixing of HSIs

$$\lambda \quad \begin{array}{c} \text{[Red square]} \\ \text{pixels} \end{array} \approx \sum_{r=1}^R \begin{array}{c} \text{[Red vertical bar]} \\ \text{[Blue horizontal bar]} \end{array}$$

Spectre( $\lambda$ )

Répartition spatiale(pixel)

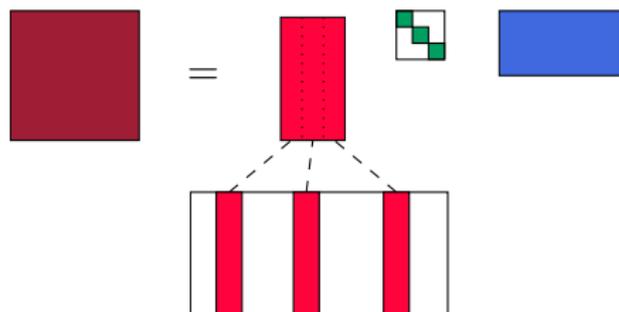
$$X \approx \sum_{r=1}^R \mathbf{u}_r \mathbf{v}_r \approx UV$$

## Challenges

**Identification problem:** Which materials are present in the scene?

**Unmixing problem:** What is the composition of each pixel?

## Additional hypotheses



$$X = UV \text{ where } U = D(:, \mathcal{K}) = DS$$

- Known Library of spectra.
- Pure pixels in the image  $\leftrightarrow D = X$

### Uniqueness

DNMF is **unique** if  $\text{spark}(D) \geq 2R$ . If  $R$  is the rank of  $X$ , then this relaxes to  $\text{spark}(D) \geq R + 1$ . [Cohen 2017, others?]

## State-of-the-art (non-exhaustive)

- **Continuous approaches** ( $X = DSV = DY$ )  
 Lasso, GLUP [Ammanouil 2014], FGNSR [Gillis 2016]  
 + Robust, optimization criterion. – Slow.
- **Greedy/Non-iterative method** ( $X = D(:, K)V$ )
  - Geometric algorithms (pure pixel hypothesis)  
 N-FINDR [Winter 1999], VCA [Nascimento 2005], SPA [Gillis 2014, Businger Golub 1965]
  - Matching pursuit approaches  
 SDSOMP[X.Fu 2013, Tropp 2006]
 + Fast – No explicit optimization criterion
- **Pixel-wise brute force algorithms**  
 MESMA [Roberts 1998], MESLUM, AUTOMCU, AMUSES  
 [Degerickx 2017]  
 + Flexible – No low rank property, Slow.
- **Statistical methods**

# Matching Pursuit ALS

An alternating nonnegative least squares method where  $U$ ,  $\mathcal{K}$  and  $V$  are estimated alternatively.

**Input:** Initial  $U$ ,  $V$ ,  $\mathcal{K}$  (Using e.g. SPA, VCA...).

**while** stopping criterion is not met,

- $\hat{U} = \operatorname{argmin}_{U \geq 0} \|X - UV\|_F^2$
- $\hat{\mathcal{K}}(i) = \operatorname{argmax}_j d_j^T \hat{U}_i$
- $\hat{V} = \operatorname{argmin}_{V \geq 0} \|X - D(:, \mathcal{K})V\|_F^2$

**Output:** Selected atoms set  $\mathcal{K}$  and abundances  $V$ .

# Pros and Cons

## Pros

- ✓ Can be adapted to N-way arrays.
- ✓ One iteration has the same complexity as geometric methods.
- ✓ Low memory requirements.
- ✓ Tries to minimize an explicit cost function.

## Cons

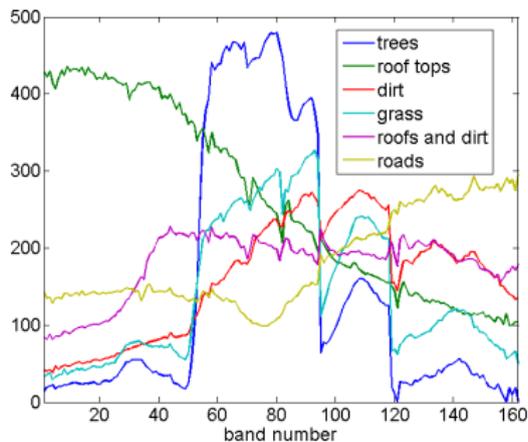
- ✗ Very sensitive to initialization.
- ✗ No convergence proof.
- ✗ May be stuck in a local minimum.

## Experiment on the URBAN HSI

	$r = 6$		$r = 8$	
	Time (s.)	Rel. err.	Time (s.)	Rel. err.
RAND-wo	0.00	7.87	0.00	11.66
d-RAND-wo	22.46 (13)	5.09	34.87 (18)	5.35
RAND-av	0.02	11.51	0.02	9.60
d-RAND-av	23.91 (13)	4.65	30.77 (15)	4.65
RAND-be	0.00	13.77	0.00	5.54
d-RAND-be	22.01 (11)	4.36	36.18 (19)	4.16
VCA	2.01	18.38	1.86	20.11
d-VCA	26.89 (15)	5.83	29.06 (14)	5.05
SPA	0.30	9.58	0.30	9.45
d-SPA	24.37 (13)	4.67	28.61 (14)	4.62
SNPA	24.34	9.63	36.72	5.64
d-SNPA	23.04 (13)	4.94	27.94 (13)	<b>3.97</b>
H2NMF	19.02	5.81	22.35	5.47
d-H2NMF	26.66 (15)	<b>4.05</b>	28.92 (14)	4.24
FGNSR-100	2.73	5.58	2.55	4.62
d-FGNSR-100	26.72 (14)	4.36	20.81 (8)	4.04

Table: Numerical results for the Urban data set.

# Experiment on the URBAN HSI



**Figure:** Spectral signatures and abundance maps identified using MPALS for the Urban data set with  $r = 6$ .

# Conclusion and Perspectives

## Conclusions

- MPALS is a relatively fast algorithm which outputs have small residuals.
- It can be easily modified to match more than one atom per spectra, and to satisfy specific constraints such as the sum to one of abundances.
- It is deterministic but very sensitive to initialization and the outputs are hard to predict with a random initialization.

## Perspectives

- Use a three-way array adaptation of MPALS for fluorescence spectroscopy.
- Develop a multiple dictionary framework making use of MPALS.
- Refine MPALS with a soft version, or with convergence proofs.

Thank you for your attention!

